

<b>Subject</b>	Fund. Of Control Sys.	<b>Course Code</b>	CT227	<b>Theoretical</b>	4 hrs / wk
<b>Semester</b>	4	<b>Prerequisite</b>	MA252	<b>Practical</b>	0 hrs / wk

### Program Learning Component

<b>Week 1-3</b>	<ul style="list-style-type: none"> <li>• <b>To understand the principle of automatic control.</b></li> <li>• <b>The ability to introduce the concept of basic control systems.</b></li> <li>• <b>To understand the concept of Controller design.</b></li> </ul>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• <b>To understand the:</b> basic principle of automatic control. Types and Models of automatic control Systems Block diagrams and Signal flow charts.</li> <li>• <b>Comprehend an overview of:</b> Relational data model..</li> </ul>	A computer & data-show. White board	
<b>Week 4-5</b>	<ul style="list-style-type: none"> <li>• <b>To understand the methods of mathematical modeling of dynamic systems.</b></li> <li>• <b>To understand the differences between open loop and closed loop control Systems.</b></li> </ul>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• <b>Understanding of the:</b> Methods of mathematical modeling of dynamic systems.</li> <li>• <b>Comprehend:</b> The feedback control Systems. The response of different control systems.</li> </ul>	A computer & data-show. White board	Ability to create a simulink control system model (linear & nonlinear)
<b>Week 6-11</b>	<ul style="list-style-type: none"> <li>• <b>To understand the behavior of dynamic systems.</b></li> <li>• <b>To understand the Errors of steady state of the dynamic systems.</b></li> <li>• <b>To understand the Stability issues of control systems.</b></li> </ul>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<ul style="list-style-type: none"> <li>• <b>understanding the:</b></li> </ul>	A computer &	Ability to simulate a

	<p>Techniques of Laplace transform, the dynamic systems behavior.</p> <p>Signal flow chart, models of dynamic systems.</p> <p>Errors associated with steady state of dynamic systems.</p> <p>Stable and Unstable Control Systems..</p>	<p>data-show.</p> <p>White board.</p>	<p>simple control systems</p> <p>Ability to analyze and simulate a control system using Matlab program</p>
<b>Week 12-14</b>	<p>• <b>Ability to analysis in Frequency response domain.</b></p> <p>• <b>Ability to use simulation tools by MATLAB for control sytems.</b></p>		
	<b>Specific Learning Outcomes</b>	<b>Resources</b>	<b>Practical</b>
	<p>• <b>Understanding the:</b></p> <p>Root locus methods for decomposition of control systems</p> <p>Controller design.</p> <p>Frequency response</p> <p>Bode Blot design.</p> <p>• Simulation process of control systems using <b>MAT LAB.</b></p>	<p>A computer &amp; data-show.</p> <p>White board</p>	<p>Ability to design the control systems using matlab.</p> <p>Obtain the transfer function practically</p>